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EFFECTS OF ROAD DESIGN AND BUILT ENVIRONMENT ON ROAD SAFETY IN DEVELOPING COUNTRIES: THE CASE OF ESKISEHIR (TURKEY)

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ABSTRACT

This paper explores effects of network design and built environment on traffic accidents. Basic objective of this study is to test simple and practical models that can predict traffic accidents in a developing country context employing similar factors used by studies conducted in developed country contexts. Data collected at 107 road segments between 2008 and 2010 in Eskisehir (Turkey) include accidents with fatalities and injuries. Two model groups are developed accordingly. The first group of models uses Binary Logit models of traffic safety. Three Binary Logit models estimated probe into distinguishing elements of road segments with no accidents in three years. The second group of models uses Count Data regression models to estimate occurrences of different accident types. For both model groups, accident types are pedestrian-vehicle, vehicle-vehicle and all accidents combined. Explanatory variables used in both group of models are derived from ambient land use characteristics, road segment properties, and traffic flow characteristics. They are slope, number of minor crossings/exits/side roads, number of lanes, type of land uses, shape of road segments, length of road segments, building coverage and number of stations, speed, and volume. Two of the direct policy implications developed from the results and accompanying discussion consider regulating public transit and improving traffic conditions and street network.

1 INTRODUCTION

2 Traffic accidents pose a real threat to the modern life in both developed and developing countries.
3 More than 1.2 million people die and 20–50 million people get injured or handicapped in traffic
4 accidents annually (1). By the year 2030, post-injury death in a traffic accident is expected to
5 become the fifth frequent cause among all causes of death; but for the youngster (10–24 age
6 group), it will rank the first (1). Injuries and disabilities caused by traffic accidents lead to further
7 widespread problems that increasingly traumatize not only the people involved in traffic accidents
8 but the people who depend on them too (2).

9 In Turkey, developing country on a fast track, a daily total of 2886 road traffic accidents
10 causes 12 people die and 552 more get injured on a daily basis (according to the statistics compiled
11 for 2009). Of special attention, 90 per cent of these accidents occur in urban areas, which is typical
12 in a fast motorizing and urbanizing background. Among total deaths and injuries, urban areas
13 account for four deaths and 300 injuries, 33 and 54 per cents, respectively (3). As a typical
14 developing country, in Turkey, number of cars is increasing fast, thereby households and
15 individuals travel more. While drivers lack experience and proper education, together with
16 pedestrians, rules in urban areas followed loosely in the face of lax controls and poor institutional
17 organization. However, vehicle kilometers travelled is steadily increasing along with uncontrolled
18 urban sprawl too. Development of urban areas poses more risks considering the layout of the land
19 uses, road structure along with other urban amenities. Therefore, risks associated with
20 transportation safety in Turkey are expected to increase more in urban areas during the years
21 ahead. Therefore, it is important to locate those risks in urban areas and devise policies that
22 minimize them.

23 Studies concerning road safety in urban areas can be traced back to 1950s in developed
24 country settings. For example, Marks (1957) is one of the first dealing with the relationships
25 between road network type and the traffic accidents (4). By comparing these two road network
26 systems (i.e., limited access (disconnected residential subdivisions) and grid system (connected
27 residential subdivisions) in terms of annual number of traffic accidents over a five year period,
28 Marks (1957) found the grid system is riskier than the limited access system (4). In terms of
29 junctions, he found that accidents concentrate around four-armed junctions, while three-armed (T)
30 junctions lead to fewer accidents (4).

31 Although Marks (1957) has been criticized for failing to consider the severity of accidents
32 and for not considering the ratio of accidents as a whole, the basic findings of his study are
33 confirmed by recent (developed country) studies conducted too (5–9). Lovegrove and Sayed
34 (2006) finds that areas with more lane miles of arterials have significantly higher accident rates
35 than areas with more local street mileage (5). Also, areas four-armed junctions have higher
36 accident rates than those with three-armed (T) junctions (5). Similarly, Ladrón de Guevara et al.
37 (2004) reports a positive relationship between percentage of roadways classified as arterials or
38 collectors and rates of total and injurious crashes (10).

39 Risk factors associated with road geometry, road environment, etc. can be estimated in
40 several ways. The most dependable method is by use of controlled ‘before–after’ cases. However,
41 ‘before–after’ studies need more sampled sites and elongated study periods. An alternative is to
42 make multidimensional cross-tabulation of accident rates by different safety factors, depending on
43 with- or without- cases (e.g., accident rates for junctions with or without signal control). However,
44 cross-tabulation is possible for a limited number of discrete variables. Furthermore, dully
45 comparing accident rates at different sites might ignore intervening variables such as geometry,
46 design, existence of amenities such as transit stops, etc. (11).

47 Nevertheless, a number of previous studies have managed to investigate road safety in
48 urban areas (e.g., 12–14). Recently, accident prediction models identifying factors affecting road
49 safety in urban areas have become popular due to their advantages over other methods. Kim et al.
50 (2006), Lovegrove and Litman (2008), Lovegrove and Sayed (2006), Greibe (2003), Dumbaugh
51 and Rae (2009), Kim and Yamashita (2002) are some of the examples of accident prediction model
52 applications based on factors affecting traffic accidents in urban areas (5, 8, 11, 15–17).

1 Basic objective of this study is to test simple and practical models that can predict traffic
 2 accidents in a developing country context employing similar factors used by studies conducted in
 3 developed country contexts. Unlike models based on traffic flows only, this study considers
 4 additional contributing factors of traffic accidents, similar to those mentioned above. This objective
 5 comes with a plea of change for designing proactive measures instead of reactive measures as
 6 given in (18) for developing country contexts. As urban areas are changing fast along with
 7 motorization in urban areas of developing countries, by defining contributing factors of accidents,
 8 it will be possible to take proactive countermeasures by planning and urban design policies, instead
 9 of waiting accidents to take reactive measures, which is the general way of doing business (at least
 10 in Turkey).

11 **TRAFFIC ACCIDENT PREVENTION POLICIES IN TURKEY (ESKISEHIR)**

12 Road safety has been addressed by the United Nations General Assembly as a major global issue
 13 especially for developing countries. Recently, the General Assembly adopted Resolution 64/255
 14 “Improving Global Road Safety” to improve road safety and reduce road traffic deaths by 50 per
 15 cent till 2020 in the “Decade of Action for Road Safety” from 2010–2020 and called on member
 16 states to declare their own action plans for the decade. Accordingly, the Road Safety Action Plan
 17 was developed by the Turkish National Police Agency in cooperation with the relevant institutions
 18 and agencies to prevent road traffic accidents, minimize fatalities and injuries, and mitigate their
 19 impacts in Turkey. One of the main tasks defined in the action plan is to decrease risks at accident
 20 black spots. As most of the accidents occur in urban areas as stated above, it is important to find
 21 ways to account for black spots in urban areas and identify possible routes of proactive measures.

22 In this manner, Eskisehir (Turkey), a fast growing mid-sized metropolitan city supplies
 23 suitable backdrop for developing country context. Eskisehir is situated in North-Western part of
 24 Mid-Anatolia region of Turkey. Eskisehir is one of the industrial and educational centers of Turkey
 25 associated with heavy industries along with two state universities. The city has a compact urban
 26 form, and a population size around 700,000 with high rates of pedestrian and bicycle trips. Public
 27 transit in the city relies on two light rail lines along 76 public bus transit lines covering all the
 28 metropolitan area. Private car ownership rate is around 155 per thousand people, which makes
 29 Eskisehir the third among the metropolitan cities of Turkey. In eight years, private car ownership
 30 in Eskisehir has increased 55 per cent from 100 to 155 per thousand people (19, 20), which
 31 inevitably increased traffic accident risks.

32 From 2005 to 2010, traffic accidents in Eskisehir had increased by 28 per cent (with an
 33 annual compound of 4.23 per cent) from 857 in 2005 to 1099 in 2010. Although number of deaths
 34 in traffic accidents monotonously decreased from 22 in 2005 to 16 (28 per cent decrease), number
 35 of injured increased by 30 per cent from 1246 to 1623 (with an annual compound of 4.50 per
 36 cent)—it should be noted that although emergency responses regarding traffic accidents improved
 37 a lot in Turkey, however, there are cases that heavily injured at accident site is generally coded as
 38 injured without no follow-up of his/her well-being, the person might die because of his/her injuries,
 39 so caution is required when interpreting number of deaths.

40 Steady increase in urban traffic accidents can partially be attributed to fast motorization
 41 and the urban backdrop. Besides, urban road safety is neglected as road safety concerns are
 42 generally restricted to inter-urban roads. This inevitably causes capacity deficiencies in urban areas
 43 to tackle accident risks (2).

44 **DATA**

45 Data on traffic accidents with fatalities or injuries had been retrieved from Traffic Information
 46 System (TIS), which is operational since 2003 is a centralized computer-based accident database
 47 based on paper-based traffic accident reports filled at accident sites by attending officers. A typical
 48 record includes date, time of day, location, type of the accident, number of the vehicles involved in

1 the accident, code of the highway, GPS measurements, age, sex, intoxication of the driver, weather
2 conditions, lighting conditions, vehicle type, and number of persons injured/killed.

3 Approximately, more than 100,000 traffic accidents worth of data are stored in TIS
4 annually. Therefore, it is possible to use spatial as well as non-spatial analyses to compare effects
5 of traffic accident prevention policies. Accordingly, data used in this study are organized in three
6 steps. Firstly, traffic accident data are queried from TIS, and points of traffic accidents are created
7 in GIS environment by using GPS measurements. Secondly, the locations of these data are cross-
8 checked with locations and false recordings are corrected if there is any unfitting condition—
9 nearly 25 per cent of the data come with wrong geospatial coordinates. Digital maps and satellite
10 images of the study area are used to determine ambient land use characteristics of road segments
11 under scrutiny. Lastly, all pertinent variables are merged under a single working data set.

12 In this study, traffic accident data regarding 107 road segments with a total of 110.98 km
13 with 1,415 traffic accidents have been assembled in the research database. Of these 107 road
14 segments, 38 road segments have 4 lanes (35.5 per cent), 37 have 3 lanes (34.6 per cent), 20 have 6
15 lanes (18.7 per cent), and 12 have 2 lanes (11.2 per cent). Considering ambient land use
16 characteristics, 37 road segments are in mixed-use (CBD) environment (34.6 per cent), the
17 remaining of the road segments fall in single (monotonous) land uses: 34 are in residential (31.8
18 per cent), 15 are in light industry (14.0 per cent), 13 are in non-urban (12.1 per cent), and 8 are in
19 industrial areas (7.5 per cent).

20 As regards fatal or injurious accidents at 107 road segments, it is found that 2005 is the
21 year of minimum values, 2007 is the year of maximum values (Table 1). Although we have annual
22 data of traffic accidents from 2005 to 2010, the independent variables compiled are available only
23 for the last three years, i.e., 2008–2010. Therefore, we have used accident data for the combined
24 2008–2010 period in the models developed in this study. Note that accidents at 107 road segments
25 generally account for more than 40 per cent of all (fatal and injurious) accidents in Eskisehir
26 annually.

27 *TABLE 1 AROUND HERE*

28 The data compiled for the models for the three year period at 107 road segments give use
29 46 % of all accidents in Eskisehir (Table 1), which is a reasonable amount for deriving inferences
30 about traffic accidents. For the dependent model variables, we rely on the TIS database for accident
31 classification that considers accident involvements such as Pedestrian-Vehicle (P-V) and Vehicle-
32 Vehicle (V-V) accidents (Table 2).

33 *TABLE 2 AROUD HERE*

34 For the 2008–2010 term, P-V accidents are mostly confined to the immediate vicinity of
35 the city center, which is mostly pedestrianized and served by newly built LRT. The first three of
36 most frequent P-V accident road segments that constitute 20 per cent of all P-V accidents are near
37 the city center. These three most frequent road segments are followed by a road segment on the
38 intercity by-pass road. When peeked, we run into a residential area neighboring the road segment
39 that might be the cause of congregation of P-V accidents there. Therefore, an early conclusion can
40 be made that P-V accidents generally occur when pedestrians are abundant regardless of the road
41 type—three types of road types are identified in this study, i.e., straight, curved and warped (Figure
42 1).

43 *FIGURE 1 AROUND HERE*

44 As regards V-V accidents, we come across a congregation of accidents on the intercity by-
45 pass road. 25 per cent of 1027 V-V accidents occur on any of the road-segments of this road, which
46 represent 11 per cent of sampled road segments (or 16 per cent in terms of their total length). One
47 of the reasons why by-pass road has become risky in terms of traffic accidents is that the road has
48 assumed the role of an intra-urban arterial road too. Therefore, mix of the traffic on the road
49 including pedestrians has increased the risk of traffic accidents on the road. Most of the cities in
50 Turkey have such kind of by-pass roads that has assumed these dual purposes in time. This is
51 mainly because of the urban expansion encroaching on the bypasses.

1 MODEL DEVELOPMENT

2 Of special interest in this study may be the locations where no traffic accident happened. In three
3 years from 2008–2010, 36 and 16 of the 107 sampled road segments witnessed no P-V and V-V
4 accidents, respectively—only at 14 road segments, there was no traffic accident at all (Table 2). A
5 Binary Logit Models are used to unearth the factors of road safety at these road segments in terms
6 of different classifications: *Model 1A: P-V, Model 1B: V-V, Model 1C: All*.

7 The rest of the models are used to account for the number of accident occurrences. Data
8 regarding these accidents are suitable for count data models of various types depending on the
9 frequency distribution; besides, previous research support use of count data models for accident
10 predictions (18, 21–29). In line with the previous research, extensions to the norm model, the
11 Poisson regression model, are also utilized to account for any diversions from the norm distribution
12 of the data generation process (i.e., the Poisson distribution). The models estimated are given as
13 follows (selected models in terms of model fit are given in bold characters):

14 *Model 2A1: Poisson regression model of P-V Accident Occurrences*

15 *Model 2A2: Zero Inflated Poisson regression model of P-V Accident Occurrences*

16 ***Model 2A3: Negative Binomial regression model of P-V Accident Occurrences***

17 *Model 2A4: Zero Inflated Negative Binomial model of P-V Accident Occurrences*

18

19 *Model 2B1: Poisson regression model of V-V Accident Occurrences*

20 *Model 2B2: Zero Inflated Poisson regression model of V-V Accident Occurrences*

21 *Model 2B3: Negative Binomial regression model of V-V Accident Occurrences*

22 ***Model 2B4: Zero Inflated Negative Binomial model of V-V Accident Occurrences***

23

24 *Model 2C1: Poisson regression model of All Accident Occurrences*

25 *Model 2C2: Zero Inflated Poisson regression model of All Accident Occurrences*

26 *Model 2C3: Negative Binomial regression model of All Accident Occurrences*

27 ***Model 2C4: Zero Inflated Negative Binomial model of All Accident Occurrences***

28 The norm Poisson regression model assumes that the conditional frequency of traffic
29 accidents at the i^{th} urban road segment, y_i is independently and identically distributed with the
30 Poisson probability mass function given mean parameter, μ_i , as follows (21, 30–32):

$$p(y_i|\mu_i)_P = \frac{e^{-\mu_i}(\mu_i)^{y_i}}{y_i!} \quad (1a)$$

31

32 The independent variables used in the Poisson regression model are associated with the
33 mean and variance parameter via the exponential mean function (Eq. 2a). Negative Binomial
34 regression model assumes that variance differs from mean as in Eq. 2b.

35

$$E(\mu_i|\mathbf{x}_i)[= V(\mu_i|\mathbf{x}_i)] = \exp(\boldsymbol{\beta}'\mathbf{x}_i) \quad (2a)$$

$$E(\mu_i|\mathbf{x}_i, \varepsilon) = \exp(\boldsymbol{\beta}'\mathbf{x}_i + \varepsilon) \quad (2b)$$

36

37 Parameter $\exp(\varepsilon)$ in Eq. 2b has Gamma Distribution with mean 1 and variance equal to α
38 which changes the probability density function as in Eq. 3.

39

$$p(y_i|\mu_i, \varepsilon)_{NB} = \frac{e^{-\mu_i \exp(\varepsilon)} (\mu_i e^\varepsilon)^{y_i}}{y_i!} \quad (3)$$

40

41 Integrating ε out of Eq. 3 gives the probability distribution function of Negative Binomial
42 regression as in Eq. 4.

43

$$p(y_i|\mu_i)_{NB} = \frac{\Gamma(\theta + n_i)}{\Gamma(\theta)n!} u_i^\theta (1 - u_i)^{n_i} \quad (3)$$

1 where $u_i = \theta(\theta + \mu_i)$ and $\theta = 1/\alpha$. Negative Binomial regression model relaxes the equality of
2 mean and variance parameters by changing variance to $V(\mu_i|\mathbf{x}_i) = E(\mu_i|\mathbf{x}_i)[1 + \alpha E(\mu_i|\mathbf{x}_i)]$.

3 Zero Inflated extension of both Poisson and Negative Binomial models (ZIP models)
4 depends on a selection process to distinguish true zeros from excess zeros. The separation depends
5 on the probability q_i such that $y_i = 0$ with probability q_i . This separation process depends on a
6 Binary Logit model of true zeros.

$$p(y_i = 0|\mu_i)_{ZIP} = q_i + (1 - q_i)p(y_i = 0|\mu_i) \quad (3a)$$

$$p(y_i = j > 0|\mu_i)_{ZIP} = (1 - q_i)p(y_i = j > 0|\mu_i) \quad (3b)$$

8 where left hand side probabilities, p , in Eq. 3a and Eq. 3b might be Poisson or Negative Binomial
9 depending on the model. The models are estimated by LIMDEP 9.0 econometric software. The
10 remaining sets of equations including log-likelihood functions and variances of estimators in the
11 models can be found in (21–23).

12 FINDINGS OF THE MODELS

13 How Risky are The Road Segments?

14 Three Binary Logit models are estimated to account for pedestrian, vehicle and all accidents, i.e.,
15 *Model 1A: P-V, Model 1B: V-V, Model 1C: All*. The results of the models are given in Table 3. All
16 models indicate significant departures from restricted models with only the constant variables.
17 Results of *Model 1A: P-V* highlight four variables that are effective on pedestrian accidents on the
18 positive side: Traffic Volume, Number of Links (per 100 mt.) and Number of Transit Stops (per
19 100 mt.) and Mixed Land Use. All these variables are proxies for possible pedestrian and vehicle
20 conflicts. In a typical developing county like Turkey, where motorization trend is on the brink of
21 exponential surges, future seems bleak in this respect. In the near future, unless extensive proactive
22 measures to control vehicle flows are taken, pedestrian accidents are expected to rise.

23 TABLE 3 AROUND HERE

24 Number of links that merges with the road segment and transit stops are the remaining
25 sources of pedestrian and vehicle conflicts—significance of parameter estimate for transit stops is
26 on the edge though. Both of the variables affect number of pedestrians and/or vehicles in the road
27 segment positively. Links that merges with the road segment are for left or right turns increase
28 risks of accidents. In the case of transit stops, existence of passengers crossing the street to reach
29 transit stops is an incessant source of traffic accidents in the developing countries. This is mainly
30 due to the lack of (local) expertise to locate transit stops and to take necessary precautions around
31 transit stops (26, 27). A plain solution to this might be to reduce the number of transit stops. But
32 this solution has to be ruled out given the heavy usage of transit systems in the developing
33 countries.

34 Combining with the early conclusion given above, we may further say that especially road
35 segments near pedestrianized area in the city center are prone to P-V accidents due to increased
36 volumes serving car-free areas. Because city center consist of mixed-land uses predominantly, we
37 expect all kinds of traffic congregating around pedestrianized area for a multitude of purposes.

38 Three variables seem to increase safety in terms of P-V accidents: Two Lane Roads,
39 Residential Land Use and Straight Roads. The city areas characterized by these variables generally
40 shoulder mixed land use areas in the city center. This characteristic can be generalized to almost all
41 of the mid-sized cities and metropolitan areas in Turkey. However, the analyses here misses one
42 important point that road segments does not include unsignalized (four-armed) intersections, which
43 cause traffic accidents (4–9)—number of links counts minor links for diverges from or merges to
44 the road segment.

1 Regarding the vehicle accidents accounted by *Model 1B:V-V*, safety is related to fewer
 2 variables: after controlling for land uses, two and four lane roads promotes safety. Risk increasing
 3 variable is the number of transit stops in this category. That might seem counter-intuitive in the
 4 case of vehicle only accidents. A possible explanation is the mix of the traffic and the existence of
 5 the paratransit aggressively looking for passengers especially, who are generally gathered around
 6 transit stops. The similar result obtained for pedestrian accidents suggest a closer look into the
 7 transit stops when traffic accident related safety policies are being prepared.

8 On the contrary, two and four-lane roads turn out to be safe havens for vehicular traffic—
 9 both coefficient estimates are significant and positive. Two separate reasons can be developed for
 10 the effects of these variables. Four-lane roads are supplied with median refuge that separates traffic
 11 in opposite directions. This is supposed to increase safety on four lane road sections. For two lane
 12 roads which are abundant in dense and predominantly residential areas, driving comes to a more
 13 considerate level, possibly by psychologically driven instincts. The result obtained for two lane
 14 roads is also supported similar result obtained for pedestrian accidents. *Model 1C: All* reveal
 15 results no different from the results and variables used for *Model 1B: V-V*. Probably, the similar
 16 result can be explained by very few number of no accident road segments.

17 **What are the Contributing Factors behind Accidents?**

18 Three groups of count data regressions are carried out with different variation, as given in the
 19 previous section. The results of best performing models are presented in Table 4. According to
 20 *Model 2A3: P-V* results, traffic volume, number of links connected to the road segment, and mixed
 21 land use turn out to be significant factors increasing pedestrian accidents. These variables were
 22 also found to increase vehicle-vehicle and all accidents too—(positive and significant) results of
 23 *Model 2B4: V-V* and *Model 2C4: All* confirm this. The reasons well discussed above are also valid
 24 here. However, these results should not give way to policies that decrease number of links, transit
 25 stops. Nor should we suggest policy makers to change mixed land uses to monotonous land uses,
 26 which increase trip lengths, private car usage, thereby unsustainability in transportation. Instead,
 27 results imply that precautions should be taken in areas associated with increasing values of these
 28 accident-increasing variables. Especially, around transit stops and connections of minor roads to
 29 major roads, traffic calming policies are advised to decrease risks of accidents.

30 *TABLE 4 AROUND HERE*

31 As for the road structure, straight and four-lane roads are found to decrease pedestrian
 32 accidents. Reasons for these results might be related to better visibility and presence of median
 33 refuge that protects pedestrians—nearly all four-lane roads have median refuges in Turkey.
 34 However, care has to be taken here as median refuge is not a natural extension of accident
 35 prevention strategy. There are examples of median refuges that cause traffic accidents too.
 36 According to field studies conducted by the second author, in Ankara, the capital of Turkey, when
 37 road segment with median refuge popular for pedestrian accidents is closely inspected; cause of
 38 accidents is found to be bushy trees blocking visibility for both drivers and pedestrians. Therefore,
 39 care must be taken, especially for micro design elements of the road infrastructure that cause all
 40 kinds of accidents. When this result is combined with the similar result for vehicle only
 41 accidents—four-lane roads also decrease vehicle only accidents too—one may say that four lane
 42 roads installed with refuges increase overall safety.

43 Further notices should be given to median refuge that is used for both separating opposing
 44 traffic flow and supplying safe passage for passengers in urban areas. Intercity by-pass road (a six
 45 lane road) has also a median refuge, which was intended to separate opposing flows only, not for
 46 supplying a safe ground for pedestrians who find themselves in-between opposing flows. When
 47 urban development encroaches the by-pass road—this is not unusual in developing countries as the
 48 urban development is on the fast track too—number of pedestrians trying to cross wide by-pass
 49 roads increase; any accident on these roads generally end up with fatalities.

1 CONCLUSION AND DISCUSSION

2 In general, variables of speed, road segment length, and number of transit stops are related to
3 traffic accidents. Monotonous land uses such as industrial and residential land uses are less related
4 to traffic accidents, whereas mixed-use (CBD) land uses are more related. While straight road
5 segments improve road safety due to better visibility, two and four lane roads are found to improve
6 road safety.

7 A strong internal correlation within the data is a major problem for this study. Variables
8 describing speed tend to correlate strongly with other variables like traffic volume, number of
9 lanes, etc. Therefore, the safety effects from a single explanatory variable were difficult to estimate
10 since it may be affected by other variables in the model.

11 Studies conducted in developed country contexts find significant effects of speed and
12 volume as well as built environment on traffic accidents (e.g., 15, 24, 25). Similar results obtained
13 in a developing country context point to universality traffic accident causes in terms of these
14 variables. This further suggests that similar precautions should be adopted in developing countries
15 in terms of road structure.

16 In terms of built environment and transportation, it is for sure that developed and
17 developing countries differ a lot (26, 27). Whereas developing country context is dense, fast
18 urbanizing, developed country context is less dense and urbanizing slowly. One of the main
19 contributing factors to traffic accidents in developing countries is the urbanization rate which
20 should be disciplined to increase road safety in urban areas.

21 Studies conducted in developed country contexts (e.g., 6, 7, 8, 18, 21-29, 33, 34) obtain
22 similar results as this study conducted in a developing country context produce: roadway
23 characteristics such as curvature and slope are found to affect traffic accidents ubiquitously.
24 Therefore, one may say that given that drivers follow traffic rules, the basic findings in terms of
25 roadway characteristics obtained in developed country contexts can be used for developing
26 countries.

27 Departures from models developed and estimated in the developed countries context
28 (although mainly in USA) are related to idiosyncratic characteristics of a developing country
29 regarding urban transportation systems (35, 36). Two of the most important variables in this
30 context are number of transit stops and number of minor roads linked to road segments. In Turkey,
31 transit stops are instituted by municipalities according to demand for the transit system. There is no
32 rule of interspacing transit stops; one may come across transit stops interspaced shorter than 200
33 mt. in the city center without much respect to ambient traffic conditions and roadway
34 characteristics. In terms of reactive safety measures, the usual practice in Turkey as in all
35 developing countries, location of a transit stop usually changes if an accident causing death or
36 injury occurs.

37 Another finding states that mixed land use increases traffic accidents. Generally, city
38 centers and their immediate vicinities are associated with mixed land uses. Mixed land use attracts
39 more traffic during the day in addition to pedestrians, therefore, traffic in these areas become dense
40 (road segments in mixed land use areas averages second in terms of average hourly traffic volumes
41 in Eskisehir). Moreover, in the city center where parking are generally unregulated at roadsides,
42 accident risk increases when some of the vehicles try to park, transit vehicles make frequent stops
43 for passengers, and while others try to maintain their courses.

44 One must also take into consideration the paratransit vehicles without no designated stops.
45 Paratransit which is partially regulated (in terms of route and vehicle size) is another source of risk
46 especially in city centers. Paratransit vehicles which assume stop-go cycles for taking or dropping
47 passengers are more inclined to make risky maneuvers around transit stops (location of which are
48 risky) for prospective passengers. In a fast changing urban setting and heavy patronage of public
49 transit, location of transit stops and design of minor links come without no safety precautions. In
50 this manner, proactive perspective for road safety is badly needed in developing countries.

51 Policy Implications

1 True, when it comes to the backstage, developing countries deserve more thoughtful and thorough
 2 approach in terms of variables developed for traffic accidents, thereby safety. As WHO and Aeron-
 3 Thomas and Jacobs stress, till 2030, expected deaths are mostly will be observed in low-income
 4 countries, which will be followed by lower middle-income countries (1, 2). Although results of this
 5 study conducted in a developing country confirms results obtained in developed country setting in
 6 terms of roadway characteristics, nature of the traffic, their communication with the immediate
 7 environment deserves a lot more in terms of policies. While mixed land use is tagged as
 8 sustainable for creating shorter vehicular trips and endorsed in developed country setting, mixed
 9 land use in developing countries seem to cause traffic accidents. Solution to this is not to decrease
 10 mixed land uses, instead proactive stance is needed to remedy deficiencies by using design and
 11 control elements simultaneously. Some of the direct policy implications can be summarized as
 12 follows:

- 13 1. *Regulating public transit*: Two policy areas seem to be appropriate under this category. The
 14 first one is the location of transit stops. Although the current study reveals results about the
 15 number of transit stops—as the number of transit stops increase in a road segment,
 16 accident risk accidents increase. This result is corollary to the risks associated with the
 17 location of transit stops—however this has to be verified by additional empirical
 18 researches. Location of transit stops is not restricted to city centers. According to daily
 19 news in Turkey, there are numerous traffic accidents in which vehicles overrun transit
 20 stops, thereby causing fatalities and injuries.
- 21 2. *Improving traffic conditions and street network*: In an environment where traffic is
 22 associated with different kinds of vehicles in terms of type, size, quality and age in
 23 addition to unregulated street space and fast motorization, control of traffic (in terms of
 24 signalization) and safety-improving (or risk decreasing) design are crucial. However, urban
 25 planning, street design and transportation planning activities are practiced independently.
 26 Coordination between these related areas in developing cities is critical in terms of road
 27 safety. Therefore capacity building for a more unified and coordinated ways of urban
 28 governance can be the most significant policy area in terms of road safety.
 29

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6**TABLE 1 Accidents on 107 Road Segments (2005–2010)**

Year/Period	Number of Accidents at 107 Road Segments (per cent of all accidents in the year or the period)	Summary Statistics of Accidents			
		Median	Av.	Max.	Std. Dev.
2005	350 (41 %)	2	3.27	26	4.14
2006	446 (50 %)	3	4.17	22	4.87
2007	584 (54 %)	3	5.46	30	6.16
2008	482 (49 %)	2	4.50	25	5.55
2009	447 (44 %)	3	4.18	28	5.16
2010	486 (44 %)	4	4.54	23	4.84
2008–2010	1415 (46 %)	9	13.22	75	14.38

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8

TABLE 2 Model Variables

Variables	%	Mean	Median	Std. Dev.	Min.	25%	75%	Max.
No P-V Accidents (36 Road Segments)	33.6							
No V-V Accidents (16 Road Segments)	15.0							
No Accidents (14 Road Segments)	13.1							
# of Accidents (P-V Accidents)		3.62	2	5.55	0	0	5	38
# of Accidents (V-V Accidents)		9.60	5	10.28	0	2	14	46
# of Accidents (All Accidents)		13.22	9	14.44	0	3	21	75
Length (km.)		1.04	0.89	0.50	0.24	0.71	1.33	3.48
Speed (km/h)		32.18	27	16.94	12	21	39	102
Traffic Volume (# of 2-way pcu per hour., <i>ln</i>)		5.17	5.47	1.36	0.62	4.41	6.14	7.08
Slope (x100 %)		0.01	0.01	0.02	0.00	0.00	0.02	0.15
# of Transit Stops per 100 mt.		0.48	0.00	0.86	0	0	1	4
# of Links per 100 mt.		0.04	0.00	0.08	0		0.07	0.30
Building Coverage (%)		58.54	60.39	32.48	0.00	30.66	90.95	100
Land Use #1: Light Industry	14.0							
Land Use #2: Mixed Use	34.6							
Land Use #3: Residential	31.8							
Land Use #4: Industrial	7.5							
Land Use #5: Non-urban	12.1							
Road Type #1: Straight	51.4							
Road Type #2: Warped	29.9							
Road Type #3: Curved	18.7							
# of Lanes: 2	11.2							
# of Lanes: 3	34.6							
# of Lanes: 4	35.5							
# of Lanes: 6	18.7							
Sample Size								

TABLE 3 Results of No Accident Binary Logit Models

Variables	<i>Model 1A: P-V</i>		<i>Model 1B.V-V</i>		<i>Model 1C: All</i>	
	Coeff.	<i>p</i>	Coeff.	<i>p</i>	Coeff.	<i>p</i>
Constant	2.26	0.12	-3.42	0.00	-3.52	0.00
Length (km.)						
Speed (km/h, <i>ln</i>)						
Traffic Volume (<i>ln</i>)	-0.53	0.03				
Slope (x100 %)						
# of Transit Stops per 100 mt.	-8.95	0.15	-15.19	0.08	-19.41	0.08
# of Links per 100 mt.	-0.60	0.08				
Building Coverage (%)						
Land Use #1: Light Industry						
Land Use #2: Mixed Use	-1.99	0.05				
Land Use #3: Residential	1.35	0.09				
Land Use #4: Industrial	1.69	0.18	2.76	0.07	3.19	0.00
Land Use #5: Non-urban						
Road Type #1: Straight	1.49	0.03				
Road Type #2: Warped						
Road Type #3: Curved						
# of Lanes: 2	3.44	0.03	2.69	2.62	0.01	0.11
# of Lanes: 3						
# of Lanes: 4			2.44	0.01	2.17	0.02
# of Lanes: 6						
Log-Likelihood with Constant	-68.34		-45.14		-41.51	
Log-Likelihood (Model)	-37.32		-30.98		-27.4	

TABLE 4 Results of Count Data Regression Models

Variables	<i>Model 2A3: P-V</i>		<i>Model 2B4: V-V</i>				<i>Model 2C4: All</i>			
	<i>Neg. Binomial R.</i>		<i>ZIP Neg. Binomial R.</i>				<i>ZIP Neg. Binomial R.</i>			
	Coeff.	<i>p</i>	Coeff.	<i>p</i>	<i>ZIP Model</i>		Coeff.	<i>p</i>	<i>ZIP Model</i>	
					Coeff.	<i>p</i>			Coeff.	<i>p</i>
Constant	-2.88	0.03	1.12	0.16	-4.37	0.01	0.70	0.41	-4.85	0.01
Length (km.)	0.72	0.00	0.90	0.00			0.96	0.00		
Speed (km/h, <i>ln</i>)	0.09	0.75	-0.21	0.35			-0.17	0.47		
Traffic Volume (<i>ln</i>)	0.38	0.00	0.18	0.00			0.24	0.00		
Slope (x100 %)	-11.08	0.24	-8.39	0.25			-7.77	0.29		
# of Transit Stops per 100 mt.	1.49	0.31	-0.13	0.92			0.46	0.72		
# of Links per 100 mt.	0.35	0.01	0.20	0.03			0.21	0.02		
Building Coverage (%)	0.00	0.82	-0.01	0.03			-0.01	0.07		
Land Use #1: Light Industry										
Land Use #2: Mixed Use	1.33	0.00	0.75	0.00			0.94	0.00		
Land Use #3: Residential										
Land Use #4: Industrial									3.72	0.07
Land Use #5: Non-urban										
Road Type #1: Straight	-0.43	0.10	0.26	0.26			0.10	0.41		
Road Type #2: Warped			0.23	0.30			0.18	0.79		
Road Type #3: Curved							-0.29	0.47		
# of Lanes: 2	-0.51	0.32	-0.37	0.31			-0.41	0.10	3.88	0.11
# of Lanes: 3	-0.19	0.59	-0.46	0.05			-0.70	0.00		
# of Lanes: 4	-0.58	0.06	-0.59	0.01					1.55	0.33
# of Lanes: 6										
Alpha	0.48	2.64	0.25	0.00			0.32	0.00		
Log-Likelihood with Constant	-436.68		-720.17				-942.85			
Log-Likelihood (Model)	-232.35		-407.28				-482.56			
Log-Likelihood (Over-Dispersion)	na		-312.27				-338.84			



FIGURE 1 Classification of road segments.